



**Power In:** Power input (8.4V/2S lipo battery)

**STR IN:** Steering servo signal input

**STR OUT:** Steering servo signal output

**Gear IN:** Landing gear signal input(Will need a Y signal wire to connect the receiver and retract controller and Gyro gear signal)

**Brake IN:**Brake wheel signal input

**Brake out:** Connect to the brake wheels

**STR NOR/REV:** Steering servo Forward/Reverse switchover(The steering servo works in opposite way, push this button to adjust it into the correct direction)

**GEAR NOR/REV:** Landing gear Forward/Reverse switchover(The landing gear opened but not the Gyro function not working,Push this button to correct the Gyro function. When the landing gear closed the Gyro will turn off.)

**Gyro ST:** Gyro Gain setting(-100% ~ +100%) If the jet not running straight line, adjust the rotary switch to "-" or "+" direction.

Nose Steering Servo

RX Rudder Channel

Rudder Servo

Brake Wheel



RX Brake Channel

RX Gear Channel

Electric Retract Controller

Brake Wheel

2s Power Input

